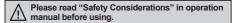
Full metal, Cylindrical, Spatter-Resistance, Cable Connector Type

Features

• High impact and wear resistance to friction with the work or metallic brush (sensing face/housing material: stainless steel)

- Reduced possibility of malfunction by aluminum scraps
- Prevent malfunction due to spatter with PTFE coating
- Excellent noise immunity with specialized sensor IC
- Built-in surge protection circuit and output short over current protection circuit
- Excellent visibility with a 360° ring type of indicator (red LED)
- Equipped with the oil resistant cable
- Protection structure: IP67 (IEC standard)





The Characteristic of Spatter-Resistance Type

The hot arc from arc welding machine is adhesive even with metals or plastics.

Therefore, normal proximity sensor might have malfunction even though there are no sensing object if the arcs are put on the sensing surface. The arcs are not adhered on the sensing part of the spatter-resistance type proximity sensor as the part is coated with PTFE against thermal resistance. Also, the protection cover sold optionally has the same function.

Durability Test

Highly resistant to the impact of removing welding sludge attached to the sensing face

Ocontinuous hitting test



Test conditions

Hitting object: 1.3kg of weight Hitting speed: 48 times per 1 min

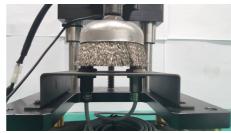
The number of hitting times: 300 thousand times

Test model: PRFAW18



<Test result>

Metallic brush test



NEW

Test conditions

Testing object: stainless cup brush Rotation speed: 80RPM Testing time: 3 hours Test model: PRFAW18



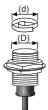
<Test result>

Effect of Aluminum Scraps

When aluminum scraps are attached or stacked at sensing side, the proximity sensor does not detect and sensing signal is OFF. However, the below cases may occur to sensing signal. In this case, remove the scraps.

(1) When the size of aluminum scraps (d) is bigger than 2/3 of the sensing side size (D)

(2) When aluminum scraps are attached on the sensing side by external pressure



Model	D (mm)
PRFAW12	10
PRFAW18	16
PRFAW30	28



Full metal, Cylindrical, Spatter-Resistance, Cable Connector Type

Specifications

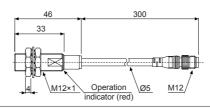
• DC 2-wire type

Model		PRFAWT12-2DO-IV	PRFAWT18-5DO-IV	PRFAWT30-10DO-IV		
Sensing distance ^{*1}		2mm	5mm	10mm		
Hysteresis		Max. 15% of sensing distance				
Standard sensing target		12×12×1mm (iron)	30×30×1mm (iron)	54×54×1mm (iron)		
Setting distance		0 to 1.4mm	0 to 3.5mm	0 to 7mm		
Power supply (operating voltage)		12-24VDC== (10-30VDC==)				
Leakage current		Max. 0.8mA				
Response frequency ^{*2}		100Hz	80Hz	50Hz		
Residual voltage		Max. 3.5V				
Affection by Temp.		Max. ±20% for sensing distance at ambient temperature 20°C				
Control output		Max. 3 to 100mA				
Insulation resistance		Over 50MΩ (at 500VDC megger)				
Dielectric strength		1,000VAC 50/60Hz for 1 min				
Vibration		1.5mm amplitude at frequency 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours				
Shock		1,000m/s² (approx. 50G) in each X, Y, Z direction for 10 times				
Indicator		Operation indicator: red LED				
Environ	Ambient temperature	mperature -25 to 70°C, storage: -25 to 70°C				
-ment	Ambient humidity	35 to 95%RH, storage: 35 to 95	%RH			
Protection circuit		Surge protection circuit, output short over current protection circuit				
Protection		IP67 (IEC standard)				
Cable		Ø5mm, 2-wire, 300mm, M12 connector (AWG22, core diameter: 0.08mm, no. of cores: 60, insulator diameter: Ø1.25mm)				
Material		Case/Nut: stainless steel 303 (SUS303, PTFE coated), washer: stainless steel 304 (SUS304), sensing side: stainless steel 303 (SUS303, PTFE coated, thickness is 0.8mm), oil resistant cable (gray): oil resistant polyvinyl chloride (PVC)				
Approva	I	C€	·			
πρρίονα			Approx. 132g (approx. 97g)			

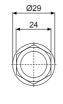
Dimensions

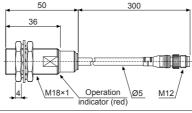
PRFAWT12-2DO-IV



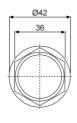


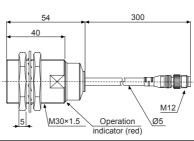
PRFAWT18-5DO-IV





PRFAWT30-10DO-IV





(A) Photoelectric Sensors

(C) Door/Area Sensors

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(I) SSRs / Power Controllers

(unit: mm)

(N) Display Units

(P) Switching Mode Power Supplies

(Q) Stepper Motors

(R) Graphic/ Logic Panels

D-3 **Autonics**

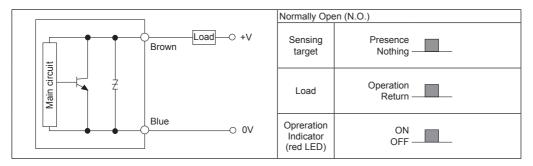
xx2: The response frequency is the average value. The standard sensing target is used and the width is set as 2 times of the standard sensing target, 1/2 of the sensing distance for the distance.

^{*3:} The weight includes packaging. The weight in parenthesis is for unit only.

XEnvironment resistance is rated at no freezing or condensation.

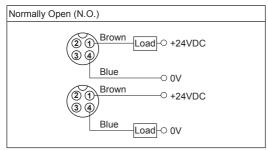
■ Control Output Diagram & Load Operating

• DC 2-wire type



Connections

DC 2-wire type (IEC standard)

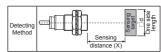


 \ggg ③, ③ are N·C (Not Connected) terminals. \ggg For the type and specifications of connector wires, please refer to G-5 page.

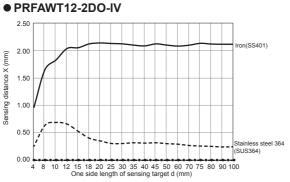
D-4 **Autonics**

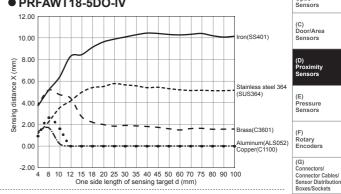
Full metal, Cylindrical, Spatter-Resistance, Cable Connector Type

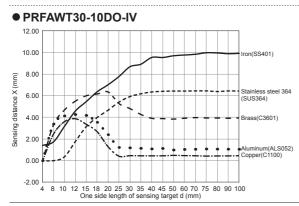
■ Sensing Distance Feature Data by Target **Material and Size**











(I) SSRs / Power Controllers

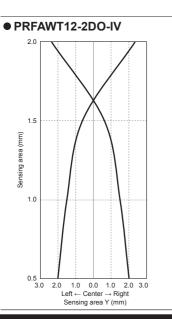
(A) Photoelectric Sensors

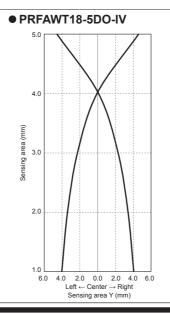
(N) Display Units

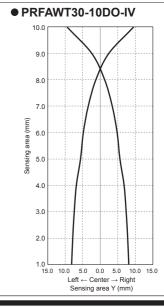
(P) Switching Mode Power Supplies

(R) Graphic/ Logic Panels

■ Sensing Distance Feature Data by Parallel (Left/Right) Movement







Autonics

PRFAW Series

Proper Usage

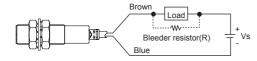
O Load connections



When using DC 2-wire type proximity sensor, the load must be connected, otherwise internal components may be damaged. The load can be connected to either wire.

O In case of the load current is small

• DC 2-wire type



It may cause return failure of load by residual voltage. If the load current is under 5mA, please make sure the residual voltage is less than the return voltage of the load by connecting a bleeder resistor in parallel with the load as shown in the diagram.

$$R \le \frac{V_s}{I}(k\Omega)$$
 $P > \frac{V_s^2}{R}(W)$

[I: Action current of load, R: Bleeder resistance, P: Permissible power] Please make the current on proximity sensor smaller than the return current of load by connecting a bleeder resistor in parallel.

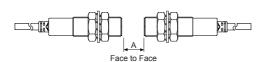
W value of Bleeder resistor should be bigger for proper heat dissipation.

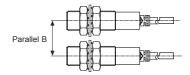
$$R \le \frac{V_s}{I_0 - loff} (k\Omega)$$
 $P > \frac{V_s^2}{R} (W)$

 $[\begin{tabular}{ll} Vs: Power supply, & lo: Min. action current of proximity sensor, \\ loff: Return current of load, P: Number of Bleeder resistance watt \\ \end{tabular}]$

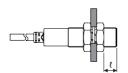
Mutual-interference & Influence by surrounding metals

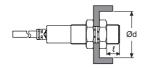
When several proximity sensors are mounted close to one another a malfunction of the may be caused due to mutual interference. Therefore, be sure to keep a minimum distance between the two sensors as below chart indicates.

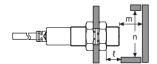




When sensors are mounted on metallic panel, it is required to protect the sensors from being affected by any metallic object except target. Therefore, be sure to provide a minimum distance as below chart indicates.







(unit: mm)

Model Item	PRFAWT12-2DO-IV	PRFAWT18-5DO-IV	PRFAWT30-10DO-IV
Α	40	65	110
В	35	60	100
l	0	0	0
Ød	12	18	30
m	8	20	40
n	40	60	100

D-6 Autonics